Sri Krishna Institute of Technology, Bangalore


## COURSE PLAN

Academic Year 2019-2020

| Program: | UG |
| :---: | :---: |
| Semester: | IV |
| Course Code: | $18 E C 45$ |
| Course Title: | Signals \& Systems |
| Credit / L-T-P: | $4 / 4-0-0$ |
| Total Contact Hours: | 40 |
| Course Plan Author: | M.Nagaraja |

Academic Evaluation and Monitoring Cell

Sri Krishna Institute of Technology
\#29,Chimney hills,Hesaraghata Main road, Chikkabanavara Post
Bangalore - 560090, Karnataka, INDIA

## Phone / Fax :08023721477/28392221/23721315

Web: www.skit.org.in , e-mail: skitprinci@gmail.com

## Table of Contents

A. COURSE INFORMATION .....  2

1. Course Overview ..... 2
2. Course Content ..... 3
3. Course Material .....  3
4. Course Prerequisites ..... 3
5. Content for Placement, Profession, HE and GATE .....  .4
B. OBE PARAMETERS ..... 4
6. Course Outcomes ..... 4
7. Course Applications. ..... 4
8. Articulation Matrix ..... 4
9. Curricular Gap and Content .....  .5
C. COURSE ASSESSMENT ..... 5
10. Course Coverage ..... 5
11. Continuous Internal Assessment (CIA) ..... 5
D1. TEACHING PLAN - 1 ..... 5
Module - 1 ..... 5
Module - 2. ..... 6
E1. CIA EXAM - 1. ..... 7
a. Model Question Paper - 1. ..... 7
b. Assignment -1 ..... 7
D2. TEACHING PLAN - 2 ..... 7
Module - 3 ..... 7
Module - 4. ..... 8
E2. CIA EXAM - 2. ..... 9
a. Model Question Paper - 2 ..... 9
b. Assignment - 2 ..... 10
D3. TEACHING PLAN - 3 ..... 10
Module - 5 ..... 10
E3. CIA EXAM - 3 . ..... 11
a. Model Question Paper - 3 ..... 11
b. Assignment - 3 ..... 11
F. EXAM PREPARATION ..... 11
12. University Model Question Paper. ..... 11
13. SEE Important Questions ..... 12

## A. COURSE INFORMATION

## 1. Course Overview

| Degree: | B.E | Program: | UG |
| :--- | :--- | :--- | :--- |
| Semester: | IV | Academic Year: | $2019-20$ |
| Course Title: | Signals \& Systems | Course Code: | $18 E C 45$ |
| Credit / L-T-P: | $4 / 4-0-0$ | SEE Duration: | 180 minutes |
| Total Contact Hours: | 40 | SEE Marks: | 60 |
| CIA Marks: | 30 | Assignment | 10 |
| Course Plan Author: | M.Nagaraja | Sign .. |  |
| Checked By: |  | Sign .. |  |
| CO Targets | CIA Target :20 | SEE Target: | 45 |

Note: Define CIA and SEE \% targets based on previous performance.

## 2. Course Content

Content / Syllabus of the course as prescribed by University or designed by institute.

| Mod ule | Content | Teaching Hours | Blooms Learning Levels |
| :---: | :---: | :---: | :---: |
| 1 | Introduction and Classification of signals: Definition of signal and systems, communication and control system as examples Classification of signals. <br> Basic Operations on signals: Amplitude scaling, addition, multiplication, differentiation, integration, time scaling, time shift and time reversal. <br> Elementary signals/Functions: Exponential, sinusoidal, step,impulse and ramp functions. Expression of triangular, rectangular and other waveforms in terms of elementary signals. | 8 | L1,L2,L3 |
| 2 | System Classification and properties: Linear-nonlinear, Time variant-invariant, causal-noncausal, static-dynamic, stableunstable, invertible. <br> Time domain representation of LTI System: Impulse response, convolution sum, convolution integral. Computation of convolution sum and convolution integral using graphical method for unit step and unit step, unit step and exponential, exponential and exponential, unit step and rectangular, and rectangular and rectangular. | 8 | L1,L2,L3 |
| 3 | LTI system Properties in terms of impulse response: System interconnection, Memory less, Causal, Stable, Invertible and Deconvolution, and step response. <br> Fourier Representation of Periodic Signals: CTF Sproperties and basic problems. | 8 | L1,L2,L3 |
| 4 | Fourier Representation of aperiodic Signals: Introduction to Fourier Transform \& DTFT, Definition and basic problems. Properties of Fourier Transform: Linearity, Time shift, Frequency shift, Scaling, Differentiation and Integration, Convolution and Modulation, Parseval's theorem and problems on properties of Fourier Transform. | 8 | L1,L2,L3 |
| 5 | The Z-Transforms: Z transform, properties of the region of convergence, properties of the Z-transform, Inverse Ztransform, Causality and stability, Transform analysis of LTI systems. | 8 | L1,L2,L3 |

- Total


## 3. Course Material

Books \& other material as recommended by university (A, B) and additional resources used by course teacher (C).

1. Understanding: Concept simulation / video ; one per concept ; to understand the concepts ; 15-30 minutes
2. Design: Simulation and design tools used - software tools used ; Free / open source
3. Research: Recent developments on the concepts - publications in journals; conferences etc.

| Modul es | Details | Chapters in book | Availability |
| :---: | :---: | :---: | :---: |
| A | Text books (Title, Authors, Edition, Publisher, Year.) | - | - |
|  | Simon Haykins and Barry Van Veen, "Signals and Systems", 2nd Edition 2008, Wiley India. ISBN 9971-51-239-4. |  | In Lib |
|  |  |  | In Lib |
| B | Reference books (Title, Authors, Edition, Publisher, Year.) | - | - |
| 1 | Michael Roberts, "Fundamentals of Signals \& Systems", 2nd edition, Tata McGraw-Hill, 2010, ISBN 978-0-07-070221-9. |  | In Lib |
| 2 | Alan V Oppenheim, Alan S, Willsky and A Hamid Nawab, "Signals and Systems" Pearson Education Asia / PHI, 2nd edition, 1997. Indian Reprint 2002. |  | In Lib |
| 3 | H.P Hsu, R. Ranjan, "Signals and Systems", Scham's outlines, TMH, 2006. |  | In Lib |
| 4 | B. P. Lathi, "Linear Systems and Signals", Oxford University Press, 2005. |  | In Lib |
| 5 | Ganesh Rao and SatishTunga, "Signals and Systems", Pearson/Sanguine. |  | In Lib |
| C | Concept Videos or Simulation for Understanding | - | - |
| 1 | https://www.youtube.com/watch?v=PHtoMPqs_Gc |  |  |
| 2 | https://www.youtube.com/watch?v=G2axsmS12Ms |  |  |
| 3 | https://www.youtube.com/watch?v=iDMwtJxXb28\&vl=en |  |  |
| 4 | https://www.youtube.com/watch?v=QLCXSxgxRPY |  |  |
| 5 | https://www.youtube.com/watch?v=wG6VUnkrO90 |  |  |
| D | Software Tools for Design | - | - |
|  | MATLAB |  |  |
| E | Recent Developments for Research | - | - |
|  |  |  |  |
|  |  |  |  |
|  |  |  |  |
| F | Others (Web, Video, Simulation, Notes etc.) | - | - |
| 1 | NPTEL VIDEOS |  | In Lib |
|  |  |  |  |

## 4. Course Prerequisites

Refer to GL01. If prerequisites are not taught earlier, GAP in curriculum needs to be addressed. Include in Remarks and implement in B. 5 .
Students must have learnt the following Courses / Topics with described Content

$\left.$| Mod <br> ules | Course <br> Code | Course Name | Topic / Description | Sem | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | | Blooms |
| :---: |
| Level | \right\rvert\,

## 5. Content for Placement, Profession, HE and GATE

The content is not included in this course, but required to meet industry \& profession requirements and help students for Placement, GATE, Higher Education, Entrepreneurship, etc. Identifying Area / Content requires experts consultation in the area.
Topics included are like, a. Advanced Topics, b. Recent Developments, c. Certificate Courses, d. Course Projects, e. New Software Tools, f. GATE Topics, g. NPTEL Videos, h. Swayam videos etc.

| Mod <br> ules | Topic / Description | Area | Remarks | Blooms <br> Level |
| :--- | :--- | :--- | :--- | :---: |
|  |  |  |  |  |
|  |  |  |  |  |
|  |  |  |  |  |
|  |  |  |  |  |

## B. OBE PARAMETERS

## 1. Course Outcomes

Expected learning outcomes of the course, which will be mapped to POs.

| Mod ules | Course Code.\# | Course Outcome <br> At the end of the course, student should be able to ... | Teach. Hours | Instr Method | $\begin{array}{\|c\|} \hline \text { Assessme } \\ \text { nt } \\ \text { Method } \\ \hline \end{array}$ | Blooms' Level |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 18EC45.1 | Understand the basic elementary signals and their classification by mathematical description. | 8 | Lecture | Slip Test | L2 |
| 2 | 18EC45.2 | Develop input output relationship for LTI system and understand the convolution operation for continuous time and Discrete signals. | 8 | Lecture | $\begin{gathered} \text { Assignme } \\ \mathrm{n} \end{gathered}$ | L3 |
| 3 | 18EC45.3 | Resolve the signals in frequency domain using Fourier transform of continuous time signal | 8 | Lecture | Assignme nt and Slip Test | L2 |
| 4 | 18EC45.4 | Apply Fourier transform representation to study and resolve the signal and system | 8 | Lecture and Tutorial | Assignme nt | L3 Apply |
| 5 | 18EC45.5 | Apply z-transform and its properties for the analysis of discrete time system using partial fraction expansion method. | 8 | Lecture | Slip test | L3 Apply |
| - | - | Total | 40 | - | - | - |

## 2. Course Applications

Write 1 or 2 applications per CO.
Students should be able to employ / apply the course learnings to ...

| Mod <br> ules | Application Area <br> Compiled from Module Applications. | CO | Level |
| :---: | :--- | :---: | :---: |
| 1 | Speech and audio processing, biological signal analysis | CO 1 | L 2 |
| 1 | Remote sensing system. | CO 1 | L 2 |
| 2 | Radars, Digital filter design. | CO 2 | L 3 |
| 2 | Distance phone calls, Digital recording, image processing. | CO 2 | L 3 |
| 3 | Radars, Digital filter design | CO 3 | L 2 |
| 3 | 3Distance phone calls, Digital recording, image processing | CO 3 | L 2 |
| 4 | Amplitude modulation, frequency multiplexing | CO 4 | L 3 |
| 4 | Circuit analysis, sampling | CO 4 | L 3 |


| 5 | Analysis of digital system,system design,automatic controls in telecommunication. | CO 5 | L 3 |
| :---: | :--- | :---: | :---: |
| 5 | Simulate the continuous system, Analysis of digital filters | CO 5 | L 3 |

## 3. Articulation Matrix

CO - PO Mapping with mapping level for each CO-PO pair, with course average attainment.

| - | - | Course Outcomes | Program Outcomes |  |  |  |  |  |  |  |  |  |  |  |  |  | - |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Mod ules | CO.\# | At the end of the course student should be able to . . |  | 2 |  | $\begin{gathered} \mathrm{PO} \\ 4 \end{gathered}$ |  | $\begin{gathered} \mathrm{PO} \\ 6 \end{gathered}$ | PO | PO | PO | $\left\lvert\, \begin{gathered} \mathrm{PO} \\ 10 \end{gathered}\right.$ | $\begin{array}{\|c\|c\|} \hline \mathrm{PO} & \mathrm{PO} \\ 11 & 12 \\ \hline \end{array}$ | $\mathrm{PS} \mid$ | $\mathrm{PS}$ | $\begin{aligned} & \mathrm{PS} \\ & \mathrm{O}_{3} \end{aligned}$ | $\begin{gathered} \text { Lev } \\ \text { el } \end{gathered}$ |
| 1 | 18EC45.1 | Understand the basic elementary signals and their classification by mathematical description. | 3 | 3 |  |  |  |  |  |  | 2 |  | 1 |  |  |  |  |
| 2 | 18EC45.2 | Develop input output relationship for LTI system and understand the convolution operation for continuous time and Discrete signals. | 3 | 3 |  |  |  |  |  |  | 2 |  | 1 |  |  |  |  |
| 3 | 18EC45.3 | Resolve the signals in frequency domain using Fourier transform of continuous time signal | 3 | 3 |  |  |  |  |  |  | 2 |  | 1 |  |  |  |  |
| 4 | 18EC45.4 | Apply discrete time Fourier transform representation to study and resolve the signal and system | 3 | 3 |  |  |  |  |  |  | 2 |  | 1 |  |  |  |  |
| 5 | 18EC45.5 | Apply z-transform and its properties for the analysis of discrete time system using partial fraction expansion method. | 3 | 3 |  |  |  |  |  |  | 2 |  | 1 |  |  |  |  |
| - | $17 \mathrm{EC62}$. | Average | 3 | 3 |  |  |  |  |  |  | 2 |  | 1 |  |  |  | - |
| - | PO, PSO | 1.Engineering Knowledge; 2.Probl 4. Conduct Investigations of Complex Society; 7.Environment and Su 10.Communication; 11.Project S1.Software Engineering; S2.Data B | em ex usta Man Base | An | ana | ysis; ms;' ity; ent agen | me | $\begin{aligned} & \text { esic } \\ & \text { del } \\ & \text { ic } \end{aligned}$ | $\begin{aligned} & \text { sign } \\ & \text { ern } \\ & \text { cs; } \\ & \text { Fir } \\ & 53 . W \end{aligned}$ | Veb D | Dev <br> Us <br> ndiv <br> ce: <br> Des | ign | ment 6.Th an Life-lo | g | Sol |  | ns; <br> and <br> rk; <br> in; |

## 4. Curricular Gap and Content

Topics \& contents not covered (from A.4), but essential for the course to address POs and PSOs.

| Mod <br> ules | Gap Topic | Actions Planned | Schedule Planned | Resources Person | PO Mapping |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | MATLAB | Seminar | 3rd <br> Week of March <br> 2020 | List from B4 <br> above |  |
| 2 | MATLAB to Obtain the <br> spectrum of signals | Seminar | $3^{\text {rd }}$ Week April 2020 |  | List from B4 <br> above |

## C. COURSE ASSESSMENT

## 1. Course Coverage

Assessment of learning outcomes for Internal and end semester evaluation.

| Mod Title | Teach. | No. of question in Exam | CO | Levels |
| :---: | :---: | :---: | :---: | :--- |


| ules |  | Hours | CIA-1 | CIA-2 | CIA-3 | Asg | $\begin{gathered} \text { Extra } \\ \text { Asg } \\ \hline \end{gathered}$ | SEE |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Introduction and Classification of signals ,Basic Operations on signals , Elementary signals / Functions | 8 | 2 | - | - | 1 | 1 | 2 | CO1, CO2 | L1, L2 |
| 2 | System Classification and properties: Time domain representation of LTI System | 8 | 2 | - | - | 1 | 1 | 2 | CO3, CO4 | L2, L3 |
| 3 | LTI system Properties in terms of impulse response <br> Fourier Representation of Periodic Signals | 8 | - | 2 | - | 1 | 1 | 2 | CO5, CO6 | L2, L3 |
| 4 | Fourier Representation of aperiodic Signals <br> Properties of Fourier Transform: | 8 | - | 2 | - | 1 | 1 | 2 | CO7, C08 | L2, L3 |
| 5 | The Z-Transforms | 8 | - | - | 4 | 1 | 1 | 2 | CO9, CO10 | L2, L3 |
| - | Total | 40 | 4 | 4 | 4 | 5 | 5 | 10 | - | - |

## 2. Continuous Internal Assessment (CIA)

Assessment of learning outcomes for Internal exams. Blooms Level in last column shall match with A. 2.

| $\begin{aligned} & \text { Mod } \\ & \text { ules } \end{aligned}$ | Evaluation | Weightage in Marks | CO | Levels |
| :---: | :---: | :---: | :---: | :---: |
| 1,2 | CIA Exam - 1 | 30 | CO1,CO2 | L1,L2, L3 |
| 3, 4 | CIA Exam - 2 | 30 | $\mathrm{CO}_{3, \mathrm{CO}}^{4}$ | L2, L3 |
| 5 | CIA Exam - 3 | 30 | CO 5 | L2, L3 |
| 1,2 | Assignment - 1 | 10 | CO1,CO2 | L1,L2, L3 |
| 3, 4 | Assignment-2 | 10 | $\mathrm{CO}_{3, \mathrm{CO}}^{4}$ | L2, L3 |
| 5 | Assignment - 3 | 10 | CO 5 | L2, L3 |
| 1,2 | Seminar - 1 |  | - | - |
| 3, 4 | Seminar - 2 |  | - | - |
| 5 | Seminar-3 |  | - | - |
| 1, 2 | Quiz - 1 |  | - | - |
| 3, 4 | Quiz - 2 |  | - | - |
| 5 | Quiz - 3 |  | - | - |
| 1-5 | Other Activities - Mini Project | - |  |  |
|  | Final CIA Marks |  | - | - |

## D1. TEACHING PLAN - 1

## Module - 1

| Title: |  | Appr <br> Time: | 8 Hrs |
| :---: | :--- | :---: | :---: |
| $\mathbf{a}$ | Course Outcomes | CO | Blooms |
|  | Understand the basic elementary signals and their classification by mathematical <br> description. | $\mathrm{CO1}$ | L2 |
|  |  |  |  |
|  |  | - | - |
| $\mathbf{b}$ | Course Schedule | - | - |
| Class No Portion covered per hour | CO 1 | L 2 |  |
| $\mathbf{1}$ | Introduction: Definitions of signals and a system |  |  |


| 2 | Classification of signals. | CO1 | L2 |
| :---: | :---: | :---: | :---: |
| 3 | Basic operations on signals: Amplitude and time operations | CO1 | L2 |
| 4 | Folding, Time shifting, time scaling operations | CO1 | L2 |
| 5 | Problems | CO1 | L2 |
| 6 | Problems | CO 2 | L2 |
| 7 | Elementary signals and their representation | CO 2 | L2 |
| 8 | Elementary signals viewed as interconnections of operations, | CO 2 | L2 |
| 9 | properties of systems. | CO2 | L2 |
| 10 | problems | CO2 | L2 |
| c | Application Areas |  |  |
| - | Students should be able employ / apply the Module learnings to . |  |  |
| 1 | Speech and audio processing, biological signal analysis | CO 1 | L2 |
|  |  |  |  |
| d | Review Questions |  |  |
| - |  |  |  |
| 1 | Define Signals and systems? | CO 1 | L2 |
| 2 | What are the major classifications of the signal? | CO1 | L2 |
| 3 | Explain the basic elementary signals with their mathematical equation? | CO 1 | L2 |
| 4 | Define periodic signal and non-periodic signal? | CO 1 | L2 |
| 5 | Define Energy and power signal? | CO 1 | L2 |
| 6 | Define even and odd signal? | $\mathrm{CO}_{1}$ | L2 |
| 7 | Determine whether the following systems are linear,time invariant,causal ,stable. $y(n)=\log (x(n))$. | CO1 | L2 |
| 8 | Determine whether the following systems are linear or not $\mathrm{dy}(\mathrm{t}) / \mathrm{dt}+3 \mathrm{ty}(\mathrm{t})=$ t2 $x(t) \& y(n)=2 x(n)+1 / x(n-1)$ | $\mathrm{CO1}$ | L2 |
| 9 | Determine whether the following systems are Time-Invarient or not $Y(t)=t x(t)$ \& $y(n)=x(2 n)$ | $\mathrm{CO1}$ | L2 |
| 10 | Find whether the signal $x(t)=2 \cos (10 t+1)-\sin (4 t-1)$ is periodic or not. (6) Evaluate $\sum n=(-\infty$ to $\infty$ ) e $2 n \delta(n-2)$ | CO1 | L2 |
| 11 | b) Determine whether the following signals are energy or power and calculate their energy and power. i) $x(n)=(1 / 2) n u(n)$ ii) $x(t)=r e c t(t / T o)$ iii) $x(t)=\cos 2(\Omega t)$ | $\mathrm{CO1}$ | L2 |
| 12 | Define unit step, ramp, pulse, impulse and exponential signals. Obtain the relationship between the unit step and unit ramp function. | CO1 | L2 |
| 13 | Find the fundamental period T of the signal, $x(n)=\cos (n \pi / 2)-\sin (n \pi / 8)+3 \cos (n \pi / 4+\pi / 3)$ | $\mathrm{CO1}$ | L2 |
| 14 | Determine the power of the following signals. i) $x_{1}(t)=5 \cos (50 t+\pi / 3)$ ii) $x_{2}(t)=20 \cos 50 t \cos 15 t$ | CO1 | L2 |
| 15 | Determine whether the following systems are time variant or time -invariant. i) $y(t)=t x(t) i i) y(n)=x(2 n)$ | CO 1 | L2 |
| 16 | Determine whether the following signal is periodic. If periodic , determine the fundamental period: $X(t)=3 \cos t+4 \cos (t / 2) X(t)=\cos 60 \pi t+\sin 50 \pi t$ | CO1 | L2 |
| 17 | Determine whether the following system is linear, time invariant, causal, stable and static $1 . y(n)=x 2(n) 2 . y(n)=x(-n)$ | CO1 | L2 |
| 18 | A discrete time signal is given by $x(n)=[1,1,1,1,2]$ Sketch the following signals a) $x(n-2)$ b) $\times(n+1) \quad c) \times(3-n) d) \times(n) u(n-1) \quad e) x(n-1) \delta(n-1) \quad$ f)Even samples of $x(n)$ g)odd samples of $x(n)$ | CO 1 | L2 |

## Module - 2

| Title: |  | Appr <br> Time: | 8 Hrs |
| :---: | :--- | :---: | :---: |
| $\mathbf{a}$ | Course Outcomes | CO | Blooms |
| - | Develop input output relationship for LTI system and understand the <br> convolution operation for continuous time and Discrete signals. | CO2 | L3 |
|  |  |  |  |
|  |  |  |  |
|  |  |  |  |


| b | Course Schedule | - | - |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { Class } \\ & \text { No } \end{aligned}$ | Portion covered per hour | - | - |
| 11 | ISystem Classification and properties | $\mathrm{CO}_{3}$ | L3 |
| 12 | Linear-nonlinear, | $\mathrm{CO}_{3}$ | L3 |
| 13 | Time variant-invariant | $\mathrm{CO}_{3}$ | L3 |
| 14 | causal-noncausal, | CO 3 | L3 |
| 15 | static-dynamic, | CO 4 | L3 |
| 16 | stable-unstable, invertible. | CO 4 | L3 |
| 17 | ime domain representation of LTI System: | CO 4 | L3 |
| 18 | Impulse response, convolution sum, convolution integral | CO 4 | L3 |
| 19 | Computation of convolution sum and convolution integral using graphical method for unit step and unit step, unit step and exponential |  |  |
| 20 | exponential and exponential, unit step and rectangular, and rectangular and rectangular.. |  |  |
| c | Application Areas | - | - |
| - | Students should be able employ / apply the Module learnings to . . . | - | - |
| 1 | Radars, Digital filter design. | $\mathrm{CO}_{3}$ | L3 |
| 2 | Distance phone calls, Digital recording, image processing. | CO 4 | L3 |
| d | Review Questions | - |  |
| - |  |  |  |
| 1 | The impulse response of a continuous time LTI system is given by $h(t)=e^{2 t} u(t-1)$ check whether the system is stable causal and memoryless. | CO 2 | L3 |
| 2 | A continuous time LTI system with unit impulse response $h(t)=u(t)$ and input $x(t)=e^{-a t} u(t) a>0$ find the output $y(t)$ of the system. | CO 2 | L3 |
| 3 | Find the step response for the LTI system represented by the impulse response $h(n)=(1 / 2)^{n} u(n)$. | CO 2 | L3 |
| 4 | consider a continuous time LTI system is represented by the impulse response $h(t)=e^{-3 t} u(t-1)$ determine whether it is i)stable ii) causal | CO 2 | L3 |
| 5 | Solve the differential equation, <br> $d^{2} y(t) / d t^{2}+3 d y(t) / d t+2 y(t)=2 x(t)$ with $y(0)=-1 d y(t) / d t$ with $t=0$ and $x(t)=\operatorname{cost} u(t)$ | CO 2 | L3 |
| 6 | The impulse response of a continuous time LTI system is given by $h(t)=e^{2 t} u(t-1)$ check whether the system is stable, causal and memoryless. | CO 2 | L3 |
| 7 | Find the response of the system described by difference equations $y(n)-1 / 9 y(n-2)=x(n-1)$ with $y(-1)=1, y(-2)=0$ and $x(n)=u(n)$ | CO 2 | L3 |
| 8 | find the difference equation representation for the block diagram representation of continuous time LTI system shown in figure 3c, | CO 2 | L3 |
| 9 |  response $h(t)=e^{a t} u(-t)$ is stable. Also find out whether the system is i)causal ii) memoryless | CO 2 | L3 |
| 10 | Represent the differential equation given below in direct form I and II $d^{2} y(t) / d t^{2}+3 d y(t) / d t+2 y(t)=d^{2} y(t) / d t^{2}+d x(t) / d t^{2}$ | CO 2 | L3 |
| 11 | Find the zero input response and forced response for the system described by the difference equation $y(n)-1 / 4 y(n-2)=2 x(n)+x(n-1)$ given $x(n)=u(n)$; $y(-2)=8, y(-1)=0 .$ | CO 2 | L3 |
| 12 | For the given impulse response determine whether system is memory less, | CO 2 | L3 |


|  | stable and causal justify your answer $h(n)=2^{n} u(-n)$ |  |  |
| :---: | :---: | :---: | :---: |
| 13 | Given impulse response of the system $h(n)=(1 / 2)^{n} u(n-2)$ find out step response of the system. | CO 2 | L3 |
| 14 | Draw direct form-I and direct form- II implementation for the following difference equation $y(n)-1 / 4 y(n-1)-1 / 8 y(n-2)=2 x(n)+3 x(n-1)$ | CO 2 | L3 |
| 15 | Find the step response of a LTI system if impulse response $h(t)=t^{2} u(t)$ | CO 2 | L3 |
| 16 | Obtain the response of the system given by $d^{2} y(t) / d t^{2} y(t)+y(t)=3 d x(t) / d t$ with $y(0)=-1, d y(t) / d t=d^{2} y(t) / d t^{2}=1$ and $2 e^{-t} u(t)$ | CO 2 | L3 |
| 17 | Find the difference equation for the system shown in fig. | CO 2 | L3 |

## E1. CIA EXAM - 1

## a. Model Question Paper - 1



## b. Assignment -1

| rs Code: | 17EC62 | Sem: | VI | Marks: | 30 | Time: 90 | 90 minutes |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Course: | ARM Microcontroller \& Embedded System |  |  |  |  |  |  |  |  |
| SN |  | Assignment Description |  |  |  |  | Marks | CO | Level |
| 1 |  | Define signals and systems, with appropriate examples? |  |  |  |  | 5 | CO1 | L3 |
| 2 |  | Write a note on classification of signals with suitable examples? |  |  |  |  | 5 | CO1 | L3 |
| 3 |  | Find the even and odd components of the signal$x(t)=\left(1+t^{3}\right) \cos ^{3}(10 t) .$ |  |  |  |  |  | CO1 | L3 |
| 4 |  | Find the overall operator of the system $y(n)=1 / 3[x(n+1)+x(n)+x(n-1)]$. |  |  |  |  | 5 | CO1 | L3 |
| 5 |  | Determine whether the system $y(t)=x(t / 2)$ is i) linear ii)Time invarient iii)memory iv)causal v)stable |  |  |  |  | 5 | CO1 | L3 |
| 6 |  | Sketch the following signal, hence find the even and odd component of signal, draw even and odd part of $x(t)=u(t)-r(t-1)+2 r(t-2)-r(t-3)$ |  |  |  |  | 5 | CO1 | L3 |
| 7 |  | State whether the following signals is periodic or not, if periodic find the fundamental period: $i) \times(n)=\cos (\pi n / 2)+\sin (\pi n / 2)$ ii) $)(t)=\cos (2 \pi t) \cdot \sin (2 \pi t))$ |  |  |  |  | 5 | CO 1 | L3 |
| 8 |  | Consider the system whose output is $y(t)=\cos \omega_{c}+x(t)$ determine where it is . i)memoryless ii)causal iii) linear iv)time invarient v)stable |  |  |  |  | 5 | CO1 | L3 |
| 9 |  | Sketch the signal for the following function, $x(t)=2 t$ for $t$ varies from 0 to 1 and $x(t)=4-2 t$ for $t$ varies from 1 to 2 . determine the odd component of $x(t)$. |  |  |  |  | 5 | CO1 | L3 |
| 10 |  |  2) $+y(n+z)$ |  |  |  |  | 5 | CO1 | L3 |
| 11 |  | Determine whether the following systems are time variant or time -invariant. i) $y(t)=t x(t)$ ii) $y(n)=x(2 n)$ |  |  |  |  | 5 | CO1 | L3 |
| 12 |  | Determine whether the following signal is periodic. If periodic determine the fundamental period: $X(t)=3 \cos t+4 \cos (t / 2)$ $x(t)=\cos 60 \pi t+\sin 50 \pi t$ |  |  |  |  | 5 | CO1 | L3 |
| 13 |  | Determine the power and RMS value of the following signals. i) $x_{1}(t)=5 \cos (50 t+\pi / 3)$ ii) $x_{2}(t)=20 \cos 50 t \cos 15 t$ |  |  |  |  | 5 | CO1 | L3 |
| 14 |  | Determine whether the following systems are linear,time invariant, causal ,stable. $y(n)=\log (x(n))$. |  |  |  |  | 5 | CO 2 | L3 |
| 15 |  | Determine whether the following systems are linear or not $d y(t) / d t+3 t y(t)=t 2 x(t) \& y(n)=2 x(n)+1 / x(n-1)$ |  |  |  |  | 5 | CO 2 | L3 |
| 16 |  | Determine whether the following system is linear, time invariant, causal, stable and static $1 . y(n)=x 2(n) 2 . y(n)=x(-n)$ |  |  |  |  | 5 | CO 2 | L3 |
| 17 |  | A discrete time signal is given by $x(n)=\{1,1,1,1,2]$ Sketch the following signals a) $\times(n-2)$ b) $\times(n+1) \quad c) \times(3-n) d) \times(n) u(n-1) \quad e) \times(n-$ 1) $(n-1) \quad$ f)Even samples of $x(n) \quad$ g)odd samples of $x(n)$ |  |  |  |  | 5 | CO 2 | L3 |
| 18 |  | Determine whether the system is i) Linear ii) Time Invariant iii) memoryless iv) causal v) stable <br> i) $y(t)=d / d t l^{-t} x(t)$ ) <br> ii) $y(n)=x(k+2)$ |  |  |  |  | 5 | CO2 | L3 |
| 19 |  | $\begin{aligned} & \text { Draw the signal } \\ & \text { i) } x(t)=3 r(t-1)-4 r(t-2)-6 r(t-3)+r(t) \end{aligned}$ |  |  | (t)=[lx | lu(1-t)lu(t) | 5 | CO2 | L4 |
| 20 |  | Define signals and systems, with appropriate examples? |  |  |  |  | 5 | CO 2 | L4 |
| 21 |  | Write a note on classification of signals with suitable examples? |  |  |  |  | 5 | CO 2 | L3 |
| 22 |  | Distinguish between: i) Energy signal and Power signal ii) Continuous and Discrete time signals iii) Even and Odd signal iv)Periodic and non periodic signals |  |  |  |  | 5 | CO2 | L3 |
| 23 |  | Determine the even and Odd components of the signal i) $x(t)=1+t^{2}+t \operatorname{tant}+\tan ^{2} t \cot t+\cot ^{3} t$ <br> ii) $x(t)=[\text { sint }+\operatorname{cost}]^{3}$ |  |  |  |  | 5 | CO2 | L3 |
| 24 |  | Define signals? |  |  |  |  | 5 | CO 2 | L3 |


| 25 | The impulse response of a continuous time LTI system is given by $h(t)=e^{2 t} u(t-1)$ check whether the system is stable causal and memoryless. | 5 | CO 2 | L3 |
| :---: | :---: | :---: | :---: | :---: |
| 26 | A continuous time LTI system with unit impulse response $h(t)=u(t)$ and input $x(t)=e^{-a t} u(t) a>0$ find the output $y(t)$ of the system. | 5 | CO 2 | L3 |
| 27 | Find the step response for the LTI system represented by the impulse response $h(n)=(1 / 2)^{n} u(n)$. | 5 | CO 2 | L3 |
| 28 | consider a continuous time LTI system is represented by the impulse response $h(t)=e^{-3 t} u(t-1)$ determine whether it is i)stable ii) causal | 5 | CO 2 | L3 |
| 29 | Solve the differential equation, $d^{2} y(t) / d t^{2}+3 d y(t) / d t+2 y(t)=2 x(t)$ with $y(0)=-1 d y(t) / d t$ with $t=0$ and $x(t)=\operatorname{cost} u(t)$ | 5 | CO 2 | L3 |
| 30 | The impulse response of a continuous time LTI system is given by $h(t)=e^{2 t} u(t-1)$ check whether the system is stable, causal and memoryless. | 5 | CO 2 | L3 |
| 31 | Find the response of the system described by difference equations <br> $y(n)-1 / 9 y(n-2)=x(n-1)$ with $y(-1)=1, y(-2)=0$ and $x(n)=u(n)$ | 5 | CO 2 | L3 |
| 32 | find the difference equation representation for the block diagram representation of continuous time LTI system shown in figure 3c, | 5 | CO 2 | L3 |
| 33 | Determine the conditions so that the continuous time system with impulse response $h(t)=e^{a t} u(-t)$ is stable. Also find out whether the system is i)causal ii) memoryless | 5 | CO 2 | L3 |
| 34 | Represent the differential equation given below in direct form I and $I I d^{2} y(t) / d^{2}+3 d y(t) / d t+2 y(t)=d^{2} y(t) / d t^{2}+d x(t) / d^{2}$ | 5 | CO 2 | L3 |
| 35 | Find the zero input response and forced response for the system described by the difference equation $y(n)-1 / 4 \quad y(n-$ $2)=2 x(n)+x(n-1)$ given $x(n)=u(n)$; $y(-2)=8, y(-1)=0$. | 5 | CO 2 | L3 |
| 36 | For the given impulse response determine whether system is memory less, stable and causal justify your answer $h(n)=2^{n} u(-$ n) | 5 | CO 2 | L3 |
| 37 | Given impulse response of the system $h(n)=(1 / 2)^{n} u(n-2)$ find out step response of the system. | 5 | CO 2 | L3 |
| 38 | Draw direct form-I and direct form- II implementation for the following difference equation $y(n)-1 / 4 \quad y(n-1)-1 / 8 y(n-2)=2 x(n)$ $+3 x(n-1)$ | 5 | CO 2 | L3 |
| 39 | Find the step response of a LTI system if impulse response $h(t)=t^{2} u(t)$ | 5 | CO 2 | L3 |
| 40 | Obtain the response of the system given by $d^{2} y(t) / d t^{2} y(t)+y(t)$ $=3 d x(t) / d t$ with $y(0)=-1, d y(t) / d t=d^{2} y(t) / d t^{2}=1$ and $2 e^{-t} u(t)$ | 5 | CO 2 | L3 |
| 41 | Find the difference equation for the system shown in fig. | 5 | CO 2 | L3 |

## D2. TEACHING PLAN - 2

## Module - 3

| Title: | Appr <br> Time: | 10 Hrs |
| :---: | :---: | :---: | :---: |


| a | Course Outcomes | CO | Blooms |
| :---: | :---: | :---: | :---: |
| - | At the end of the topic the student should be able to . | - | Level |
|  | Resolve the signals in frequency domain using Fourier transform of continuous time signal | CO3 | L2 |
|  |  |  |  |
| b | Course Schedule |  |  |
| Class No | Portion covered per hour | - | - |
| 21 | LTI system Properties in terms of impulse response: | $\mathrm{CO}_{3}$ | L2 |
| 22 | System interconnection, | $\mathrm{CO}_{3}$ | L2 |
| 23 | Memory less, Causal, Stable, Invertible | $\mathrm{CO}_{3}$ | L2 |
| 24 | Deconvolution, | $\mathrm{CO}_{3}$ | L2 |
| 25 | step response | $\mathrm{CO}_{3}$ | L2 |
| 26 | Fourier Representation of Periodic Signals: | $\mathrm{CO}_{3}$ | L2 |
| 27 | CTFS definition | $\mathrm{CO}_{3}$ | L2 |
| 28 | CTFS Properties | $\mathrm{CO}_{3}$ | L2 |
| 29 | Problems | $\mathrm{CO}_{3}$ | L2 |
| 30 | Problems | $\mathrm{CO}_{3}$ | L2 |
|  |  |  |  |
| c | Application Areas | - | - |
| - | Students should be able employ / apply the Module learnings to ... | - | - |
| 1 | Radars, Digital filter design | 1 | L2 |
| 2 | Distance phone calls, Digital recording, image processing | 2 |  |
|  |  |  |  |
| d | Review Questions | - | - |
| - | The attainment of the module learning assessed through following questions | - | - |
| 1 | State \& prove the following properties of FT. i) Time shifting property ii) parseval's theorem. | CO 3 | L2 |
| 2 | Obtain the fourier transform of $x(t)=t e^{-a t} u(t)$ | $\mathrm{CO}_{3}$ | L2 |
| 3 | Find the fourier transform of rectangular pulse shown below $x(\omega)=1 /(a+j \omega)^{2}$ | $\mathrm{CO}_{3}$ | L2 |
| 4 | Find the frequency response \& impulse response of the system described by differential equation $\mathrm{dy}(\mathrm{t}) / \mathrm{dt}+8 \mathrm{y}(\mathrm{t})=\mathrm{x}(\mathrm{t})$ | $\mathrm{CO}_{3}$ | L2 |
| 5 | Find the Fourier transform of i) $x(t)=t 2 \mathrm{u}(\mathrm{t}) \mathrm{u}(1-\mathrm{t})$ and ii$) \mathrm{x}(\mathrm{t})=\mathrm{t} \exp (-\mathrm{t}) \mathrm{u}(\mathrm{t}),>0$ | $\mathrm{CO}_{3}$ | L2 |
| 6 | Find the fourier transform of triangular pulse (10) $x(t)=\__{-}(t / m)=[102\|t\| / m\|t\| 0$ otherwise | $\mathrm{CO}_{3}$ | L2 |
| 7 | Obtain the exponential Fourier series of the waveform | CO 3 | L2 |
| 8 | Find the Fourier transform of rectangular pulse. Sketch the signal and its Fourier transform | CO 3 | L2 |
| 9 | Find the Fourier transform of a triangular pulse. | $\mathrm{CO}_{3}$ | L2 |
| 10 | State and prove following properties of Fourier Transformation. i) Frequency shift ii) Convolution theorem. | $\mathrm{CO}_{3}$ | L2 |
| 11 | Determine Fourier transformation of following signals. i) $x(t)=e-a t u(t) i i) x(t)=\operatorname{cost} W$ ot. | $\mathrm{CO}_{3}$ | L2 |
| 12 | Find the frequency response and the impulse response of the system described by the differential equation. <br> $d^{2} y / d t^{2}+5 d y / d t+6 y=-d / d t x(t)$. | $\mathrm{CO}_{3}$ | L2 |
| 13 | State and explain parsavel's theorem | $\mathrm{CO}_{3}$ | L2 |
| 14 | Obtain the fourier transform of the following signal $i) x(t)=e^{-a t} \quad u(t) ; a>0$ ii) $x(t)=$ delta(t) | $\mathrm{CO}_{3}$ | L2 |
| 15 | The impulse response of continuous time signal is given by $h(t)=1 / R e ~ e-t / R C$ $u(t)$ find the frequency response and plot the magnitude | $\mathrm{CO}_{3}$ | L2 |

## Module - 4

| Title: | Data Transmission and Telemetry <br> Measurement of Non - Electrical Quantities | Appr Time: | 10 Hrs |
| :---: | :---: | :---: | :---: |
| a | Course Outcomes | CO | Blooms |
| - | At the end of the topic the student should be able to | - | Level |
|  | Apply Discrete time Fourier transform representation to study and resolve the signal and system | CO 4 | L3 |
|  |  |  |  |
|  |  |  |  |
| b | Course Schedule |  |  |
| Class No | Portion covered per hour | - | - |
| 31 | Fourier Representation of aperiodic Signals: | CO 4 | L3 |
| 32 | Introduction to Fourier Transformsignals: The | CO 4 | L3 |
| 33 | Introduction to DTFT | CO 4 | L3 |
| 34 | Problems on FT | CO 4 | L3 |
| 35 | Problems on DTFT | CO 4 | L3 |
| 36 | Properties of Fourier Transform: Linearity, Time shift, | CO 4 | L3 |
| 37 | Frequency shift, Scaling, Differentiation and Integration, | CO 4 | L3 |
| 38 | Convolution and Modulation, | CO 4 | L3 |
| 39 | Parseval?s theorem | CO 4 | L3 |
| 40 | Problems | CO 4 | L3 |
|  |  |  |  |
| c | Application Areas | - | - |
| - | Students should be able employ / apply the Module learnings to . | - | - |
| 1 | Amplitude modulation, frequency multiplexing | CO 4 | L3 |
| 2 | Circuit analysis, sampling | CO 4 | L4 |
|  |  |  |  |
| d | Review Questions | - | - |
| - | The attainment of the module learning assessed through following questions | - | - |
| 1 | State and explain following DTFT properties I) Time shift ii) Linearity | CO 4 | L3 |
| 2 | Determine the DTFT of the following signal, i) $x(n)=u(n)$ ii) $x(n)=2^{n} u(-n)$ | CO 4 | L3 |
| 3 | Obtain the frequency response of the impulse response of the system described by the difference equation $y(n)-1 / 4 y(n-1)=3 x(n)-3 / 4 x(n-1)$ | CO 4 | L3 |
| 4 | Define Transfer function of the DT system and Define impulse response of a DT system | CO 4 | L3 |
| 5 | State the significance of difference equations and Write the differece equation for Discrete time system | CO 4 | L3 |
| 6 | Define frequency response of the DT system and explainWhat is the condition for stable system | CO 4 | L3 |
| 7 | Obtain the DTFT of the signal $\times[n]=2 n ~ u(-n)$ | CO 4 | L3 |
| 8 | State \& prove the following properties of DTFT. i) Convolution property ii) Frequency differentiation | CO 4 | L3 |
| 9 | Using DTFT find the total solution to the difference equation for discrete time signal. $5 y(n+2)-6 y(n+1)+y(n)=0.8 u(n)$ | CO 4 | L3 |
| 10 | Find the fourier transform of the following. $x(n)=1 ;-2 \leq n \leq 2$ $=0$; Otherwise | CO 4 | L3 |
| 11 | Find the fourier transform of $\mathrm{x}[\mathrm{n}]=$ an $u[n]$ for -13 . Determine the fourier transform of the discrete time rectangular pulse of amplitude $A$ and length $L$ i.e $\times[n]=A$ for $0=n=L-10$ otherwise | CO 4 | L3 |
| 12 | Determine the discrete time sequence where DTFT is given as $X(w)=1$ for $-W C=W=W c$ of $W C<\|w\|$ ? | CO 4 | L3 |
| 13 | Find the DTFT of the signal $x(n)=\mathrm{a}^{\text {ln] }} ;\|\mathrm{a}\|<1$ | CO 4 | L3 |
| 14 | Find the inverse DTFT of the signal $X\left(e^{\text {j } 2}\right)=3-\left(1 / 4 \mathrm{e}^{-j \Omega}\right) /-1 / 16 \mathrm{e}^{-2 j \Omega}+1$ | $\mathrm{CO}_{4}$ | L3 |
| 15 | Find the impulse response of the system having output $y(n)-1 / 4(1 / 2)^{n} u(n)$ | CO 4 | L3 |


|  | $+(1 / 4)^{\mathrm{n}} \mathrm{u}(\mathrm{n})$ |  |  |
| :---: | :--- | :---: | :---: |
| 16 | Obtain the difference equation for the system with frequency response <br> $\mathrm{h}\left(\mathrm{e}^{\mathrm{j})}\right)=1^{+} \mathrm{e}^{-\mathrm{j} 2} /\left(1-\left(1 / 2 \mathrm{e}^{-\mathrm{j} 2}\right)\right)\left(1=\left(1 / 24 \mathrm{e}^{-\mathrm{j})}\right)\right)$ | CO 4 | L 3 |
| $\mathbf{e}$ | Experiences | - | - |
| 1 |  | CO 7 | L 2 |
| 2 |  |  |  |

## E2. CIA EXAM - 2

## a. Model Question Paper - 2

| Crs <br> Code: | 18 EC 45 | Sem: | IV | Marks: | 30 | Time | 90 minutes |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Course: | Signals \& Systems |  |  |  |  |  |  |


| - | - | Note: Answer all questions, each carry equal marks. Module : 3,4 | Marks | CO | Level |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | a | Determine Fourier transformation of following signals. i) $x(t)=e^{-a t} u(t)$ ii) $x(t)=\operatorname{cost}$ Wot. | 5 | $\mathrm{CO}_{3}$ | L1 |
|  | b | Find the frequency response and the impulse response of the system described by the differential equation. <br> $d^{2} y / d t^{2}+5 d y / d t+6 y=-d / d t x(t)$. | 4 | $\mathrm{CO}_{3}$ | L2 |
|  | c | Find the DTFT of the signal $x(n)=a^{\|n\|} ;\|a\|<1$ | 3 | $\mathrm{CO}_{3}$ | L2 |
|  | d | Find the fourier transform of the following. $x(n)=3 ;-4 \leq n \leq 24$ $=0$; Otherwise | 3 | $\mathrm{CO}_{3}$ | L2 |
|  |  |  |  |  |  |
| 2 | a | State and explain parsavel's theorem | 3 | $\mathrm{CO}_{3}$ | L3 |
|  | b | Obtain the fourier transform of the following signal i)x(t)=e-at $u(t) ; a>0$ ii) $x(t)=d e l t a(t)$ | 4 | $\mathrm{CO}_{3}$ | L3 |
|  | C | The impulse response of continuous time signal is given by $h(t)=1 / \operatorname{Re~}^{-t / R C}$ $u(t)$ find the frequency response and plot the magnitude | 3 | $\mathrm{CO}_{3}$ | L2 |
|  | d | Find the inverse DTFT of the signal $X\left(e^{j \Omega}\right)=3-\left(1 / 4 e^{-j \Omega}\right) /-1 / 16 e^{-2 j \Omega}+1$ | 5 | $\mathrm{CO}_{3}$ | L2 |
|  |  |  |  |  |  |
| 3 | a | State and explain following DTFT properties I) Time shift ii) Linearity | 3 | CO 4 | L3 |
|  | b | Determine the DTFT of the following signal, i) $x(n)=u(n)$ ii) $x(n)=2^{n} u(-n)$ | 4 | CO 4 | L3 |
|  | C | Obtain the frequency response of the impulse response of the system described by the difference equation $y(n)-1 / 4 y(n-1)=3 x(n)-3 / 4 x(n-1)$ | 5 | CO 4 | L3 |
|  | d | Find the fourier transform of the following. $x(n)=1 ;-2 \leq n \leq 2$ $=0$; Otherwise | 3 | CO 4 | L3 |
|  |  |  |  |  |  |
| 4 | a | Obtain the DTFT of the signal $x[n]=2 n u(-n)$ | 3 | CO 4 | L3 |
|  | b | State \& prove the following properties of DTFT. i) Convolution property ii) Frequency differentiation | 4 | CO 4 | L3 |
|  | c | Using DTFT find the total solution to the difference equation for discrete time signal. $5 y(n+2)-6 y(n+1)+y(n)=0.8 u(n)$ | 4 | CO 4 | L3 |
|  | d | Obtain the difference equation for the system with frequency response $h\left(e^{j \Omega}\right)=1+e^{-j \Omega} /\left(1-\left(1 / 2 e^{-j \Omega}\right)\right)\left(1=\left(1 / 24 e^{-j \Omega}\right)\right)$ | 5 | CO 4 | L3 |

b. Assignment - 2

| Model Assignment Questions |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Crs Code: | Sem: | Marks: | Time: |  |  |  |
| Course: |  |  |  |  |  |  |
|  |  |  |  |  |  |  |
| SNo | Assignment Description |  |  | Marks | CO | Level |
| 1 | State proper | following prop val's theorem. | Time shifting | 7 | $\mathrm{CO}_{3}$ | L2 |


| 2 | Obtain the fourier transform of $\mathrm{x}(\mathrm{t})=$ te-atu(t) | 8 | $\mathrm{CO}_{3}$ | L2 |
| :---: | :---: | :---: | :---: | :---: |
| 3 | Find the fourier transform of rectangular pulse shown below $x(\omega)=1 /(a+j \omega)^{2}$ | 7 | $\mathrm{CO}_{3}$ | L2 |
| 4 | Find the frequency response \& impulse response of the system described by differential equation dy(t)/ $d t+8 y(t)=x(t)$ | 8 | CO3 | L2 |
| 5 | Find the Fourier transform of i) $x(t)=t 2 u(t) u(1-t)$ and $i i) x(t)=t$ $\exp (-t) u(t),>0$ | 7 | $\mathrm{CO}_{3}$ | L2 |
| 6 | Find the fourier transform of triangular pulse (10) $x(t)=\__{\text {( }} / \mathrm{m}$ ) $=[102\|t\| / \mathrm{m}\|\mathrm{t}\|$ o otherwise | 8 | CO 3 | L2 |
| 7 | Obtain the exponential fourier series of the waveform | 5 | CO 3 | L2 |
| 8 | Find the Fourier transform of rectangular pulse. Sketch the signal and its Fourier transform | 6 | $\mathrm{CO}_{3}$ | L2 |
| 9 | Find the Fourier transform of a triangular pulse. | 7 | $\mathrm{CO}_{3}$ | L2 |
| 10 | Obtain the DTFT of the signal x[n] $=2 n \mathrm{u}(-n$ ) | 8 | $\mathrm{CO}_{3}$ | L2 |
| 11 | State \& prove the following properties of DTFT. i) Convolution property ii) Frequency differentiation | 7 | $\mathrm{CO}_{3}$ | L2 |
| 12 | Using DTFT find the total solution to the difference equation for discrete time signal. $5 y(n+2)-6 y(n+1)+y(n)=0.8 u(n)$ | 8 | CO 3 | L2 |
| 13 | Obtain the difference equation for the system with frequency response <br> $\left.h\left(e^{\mathrm{i})}\right)=\mathrm{e}^{-\mathrm{e}^{\mathrm{j} \Omega} /\left(1-\left(1 / 2 \mathrm{e}^{\mathrm{j} \mathrm{R}}\right)\right.}\right)\left(1=\left(1 / 24 \mathrm{e}^{\mathrm{j} \mathrm{R}} \mathrm{R}\right)\right)$ | 7 | $\mathrm{CO}_{3}$ | L2 |
| 14 | State and explain following DTFT properties I) Time shift ii) Linearity | 8 | $\mathrm{CO}_{3}$ | L2 |
| 15 | Determine the DTFT of the following signal, i) $x(n)=u(n)$ ii) $x(n)=2^{n} u(-n)$ | 7 | CO 3 | L2 |
| 16 | Obtain the frequency response of the impulse response of the system described by the difference equation $y(n)-1 / 4 y(n-$ 1) $=3 \times(n)-3 / 4 \times(n-1)$ | 8 | $\mathrm{CO}_{3}$ | L2 |
| 17 | Find the fourier transform of the following. $x(n)=1 ;-2 \leq n \leq 2$ <br> = 0 ; Otherwise | 7 | $\mathrm{CO}_{3}$ | L2 |
| 18 | State and explain parsavel's theorem | 8 | $\mathrm{CO}_{3}$ | L2 |
| 19 | Obtain the fourier transform of the following signal $i) x(t)=e^{-a t}$ u(t);a>0 ii) $x(t)=d e l t a(t)$ | 7 | $\mathrm{CO}_{3}$ | L2 |
| 20 | The impulse response of continuous time signal is given by $h(t)=1 / R e e^{-t / R C} u(t)$ find the frequency response and plot the magnitude | 8 | CO 3 | L2 |
| 21 |  | 7 | CO 4 | L3 |
| 22 | Determine Fourier transformation of following signals. i) $x(t)=e-a t u(t)$ ii) $x(t)=\operatorname{cost}$ Wot. | 8 | $\mathrm{CO}_{4}$ | L3 |
| 23 | Find the frequency response and the impulse response of the system described by the differential equation. <br> $d^{2} y / d t^{2}+5 d y / d t+6 y=-d / d t x(t)$. | 7 | CO 4 | L3 |
| 24 | Find the DTFT of the signal $x(n)=\mathrm{a}^{(n)} ;\|a\|<1$ | 8 | CO 4 | L3 |
| 25 | Find the fourier transform of the following. $x(n)=1 ;-2 \leq n \leq 2$ $=0$; Otherwise | 7 | $\mathrm{CO}_{4}$ | L3 |
| 26 | Determine the DTFT of the following signal, i) $x(n)=u(n)$ ii) $x(n)=2^{n} u(-n)$ | 8 | $\mathrm{CO}_{4}$ | L3 |
| 27 | Obtain the frequency response of the impulse response of the system described by the difference equation $y(n)-1 / 4 y(n-$ 1) $=3 \times(n)-3 / 4 \times(n-1)$ | 7 | $\mathrm{CO}_{4}$ | L3 |


| 28 | Find the fourier transform of the following. $x(n)=4 ;-3 \leq n \leq 3$ $=0$; Otherwise | 8 | CO 4 | L3 |
| :---: | :---: | :---: | :---: | :---: |
| 29 | State and explain parsavel's theorem | 7 | CO 4 | L3 |
| 30 | Obtain the fourier transform of the following signal $i) x(t)=e^{-a}$ $u(t) ; a>0$ ii) $x(t)=d e l t a(t)$ | 8 | CO 4 | L3 |
| 31 | Using DTFT find the total solution to the difference equation for discrete time signal. $5 y(n+2)-6 y(n+1)+y(n)=0.8 u(n)$ | 7 | CO 4 | L3 |
| 32 | Obtain the difference equation for the system with frequency response <br> $h\left(\mathrm{e}^{\mathrm{j} \Omega}\right)=1^{+} \mathrm{e}^{-\mathrm{j} \Omega} /\left(1-\left(1 / 2 \mathrm{e}^{-\mathrm{j} \Omega}\right)\right)\left(1=\left(1 / 24 \mathrm{e}^{-\mathrm{j}^{\mathrm{j}}}\right)\right)$ | 8 | CO 4 | L3 |
| 33 | State and explain following DTFT properties I) Time shift ii) Linearity | 7 | CO 4 | L3 |
| 34 | Obtain the fourier transform of $x(t)=$ te-atu(t) | 8 | CO 4 | L3 |
| 35 | Find the fourier transform of rectangular pulse shown below $x(\omega)=1 /(a+j \omega)^{2}$ | 7 | CO 4 | L3 |
| 36 | Find the frequency response \& impulse response of the system described by differential equation $\mathrm{dy}(\mathrm{t}) /$ $d t+8 y(t)=x(t)$ | 8 | CO 4 | L3 |
| 37 | Find the Fourier transform of i) $x(t)=t 2 u(t) u(1-t)$ and ii) $x(t)=t$ $\exp (-t) u(t),>0$ | 7 | CO 4 | L3 |
| 38 | Find the fourier transform of triangular pulse $x(t)=(t / m)=\{102 \mid$ $\mathrm{t}\|/ \mathrm{m}\| \mathrm{t} \mid$ o otherwise | 8 | CO 4 | L3 |

## D3. TEACHING PLAN - 3

## Module - 5

| Title: | Loop and Horn Antenna and Antenna Types | Appr <br> Time: | 10 Hrs |
| :---: | :---: | :---: | :---: |
| a | Course Outcomes | CO | Blooms |
| - | At the end of the topic the student should be able to ... | - | Level |
|  | Explain the need of real time operating system for embedded system applications. Apply z-transform and its properties for the analysis of discrete time system using partial fraction expansion method. |  | L3 |
|  |  |  |  |
|  |  |  |  |
| b | Course Schedule | - | - |
| Class No | Portion covered per hour | - | - |
| 41 | IThe Z-Transforms-Definition | CO 5 | L3 |
| 42 | ROC, properties of the region of convergence, | CO 5 | L3 |
| 43 | properties of the Z-transform, | CO 5 | L3 |
| 44 | properties of the Z-transform | CO 5 | L3 |
| 45 | ilnverse Z-transform, | CO 5 | L3 |
| 46 | Causality and stability, | CO 5 | L3 |
| 47 | Transform analysis of LTI systems | CO 5 | L3 |
| 48 | Transform analysis of LTI systems., | $\mathrm{CO}_{5}$ | L3 |
| 49 | Problems | CO 5 | L3 |
| 50 | Problems. | CO 5 | L3 |
|  |  |  |  |
| c | Application Areas | - | - |
| - | Students should be able employ / apply the Module learnings to . . . | - | - |
| 1 | Analysis of digital system,system design,automatic controls in telecommunication. | CO 5 | L3 |
| 2 | Simulate the continuous system, Analysis of digital filters | CO 5 | L4 |
|  |  |  |  |


| d | Review Questions | - | - |
| :---: | :---: | :---: | :---: |
| - | The attainment of the module learning assessed through following questions | - |  |
| 1 | Define Z-Transform for a general discrete time signal x[n]. | CO 5 | 1 |
| 2 | What is ROC w.r.t. Z-Transform? | CO 5 | L3 |
| 3 | What are the properties of ROC? | CO 5 | L2 |
| 4 | What are the properties of Z-Transforms? | CO 5 | L3 |
| 5 | State and prove the properties of Unilateral Z-Transform and ROC. | CO 5 | L3 |
| 6 | Find the $Z$-Transform of $x[n]=-u(n-1)+(1 / 2)^{n} u(n)$ | CO5 | L4 |
| 7 | Determine the Z-Transform, ROC, pole and zero locations for the following signals: a) $\left.x(n)=(1 / 2)^{n} u(n)+(-1 / 3)^{n} u(n) \quad b\right) x(n)=e^{i n} 0^{n} u(n)$ | CO 5 | L3 |
| 8 | Find the inverse $Z$-Transform of , $H(Z)=\left(1+Z^{-1}\right) /\left(1-0.9 e^{j \pi / 4} Z^{-1}\right)\left(1-0.9 e^{-j / 4 / 4} Z^{-1}\right)$ | CO 5 | L3 |
| 9 | Find the inverse Z-Transform assuming a) Signal is causal; b) Signal has DTFT 1/ $\left(1-1 / 2 Z^{-1}\right)+2 /\left(1-2 Z^{-1}\right)$ | CO 5 | L3 |
| 10 | A system is described by the difference equation $y[n]-y[n-1]+1 / 4 y[n-2]=x[n]+$ $1 / 4 \times[n-1]-1 / 8 \times[n-2]$ a) Find the Transfer Function of the Inverse System. b) Does a stable and causal inverse system exist? | CO 5 | L3 |
| 11 | Define $Z$ transform? What are the two types of $Z$ transform? Define unilateral $Z$ transform. | CO 5 | L3 |
| 12 | What is region of Convergence and What are the Properties of ROC. | CO 5 | L3 |
| 13 | What is the time shifting property of Z transform, differentiation property in Z domain, convolution property of $Z$ transform.. | CO 5 | L3 |
| 14 | State the methods to find inverse Z transform. | CO 5 | L3 |
| 15 | State and prove parseval's relation for Z transform | CO 5 | L3 |
|  |  |  |  |
| e | Experiences | - | - |
| 1 |  | CO10 | L2 |
| 2 |  | CO 9 |  |

## E3. CIA EXAM - 3

## a. Model Question Paper - 3

| Crs <br> Code: | $18 E C 45$ | Sem: | IV | Marks: | 30 | Time: | 75 minutes |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

Course: Signals \& Systems

| - | - | Note: Answer any 2 questions, each carry equal marks. | Marks | CO | Level |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | a | Find the Z-transform of the sequence, and sketch the ROC and pole zero location <br> i) $x(n)=(1 / 3)^{n} \sin (\Pi / 4 n) u(n) \quad$ ii) $x(n)=a^{n} u(n)+b^{n} u(-n-1)$ | 8 | CO 5 | -1 |
|  | b | What is ROC with respect to Z -transform? What are its properties | 7 | CO 5 | L2 |
| 2 | a | Find the inverse $z$ transform of the following by partial fraction method $X(z)=\left(z^{4}+z^{2}\right) /\left(z^{2}-3 / 4 z+1 / 8\right) \quad\|z\|>1 / 2$ | 8 | CO 5 | L2 |
|  | b | Find the inverse $Z$ transform of $X(Z)$ by power series expansion method $X(Z)=1 / 1-1.5 Z^{-1}+0.5 Z^{-2}$ <br> ROC: $\|Z\|<1$ | 7 | CO 5 | L4 |
| 3 | a | A difference equation of the system is given as below determine the transfer function of the inverse system. Check whether the inverse system is causal and stable. $y(n)-y(n-1)+1 / 4 y(n-2)=x(n)+1 / 4 \times(n-1)-1 / 8 \times(n-2)$ | 8 | CO 5 | L1 |
|  | b | Determine the forced response for the following system $y(n)-5 / 6 y(n-1)+1 / 6 y(n-2)=x(n) \quad$ if input $x(n)=2^{n} u(n)$ | 7 | CO 5 | L2 |
| 4 | a | Solve the following difference equation $y(n)-1 / 9 y(n-2)=x(n-1)$ with $y(-1)=0, y(-2)=1 \quad \& x(n)=3 u(n)$ | 8 | CO 5 | L2 |
|  | b | Explain the following properties i) Convolution property ii) Initial value theorem | 7 | CO 5 | L2 |

## b. Assignment - 3

| Model Assignment Questions |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Crs Code: | 18EC45 Sem: | IV Marks: | 30 | Time: 90 | 90 minutes |  |  |
| Course: | Signals \& Systems |  |  |  |  |  |  |
| SNo | Assignment Description |  |  |  | Marks | CO | Level |
| 1 | Determine the transfer function and impulse response for the causal LTI system described by the equation using $Z$ transform $Y(n)-1 / 4 y(n-1)$ $3 / 8 y(n-2)=-x(n)+2 x(n-1)$ |  |  |  | 5 | CO 5 | L3 |
| 2 | Find the inverse $Z$ Transform of $X(z)=1 /\left(1-0.5 Z^{-2}-1+0.5 Z^{-1}-2\right)$ for ROC $\|Z\|$ $>1$ |  |  |  | 5 | CO 5 | L3 |
| 3 | Find the Z-transform of the following i) $x(n)=2 n u(-n-1)$ ii) $x(n)=(3) 2 n u(-$ n) |  |  |  | 5 | CO 5 | L3 |
| 4 | Solve the following difference equation using unilateral Z-transform $\mathrm{Y}(\mathrm{n})$ $+3 y(n-1)=x(n)$ with $x(n)=u(n)$ and the initial condition $y(-1)=1$ |  |  |  | 5 | CO 5 | L3 |
| 5 | Prove the following properties of Z-transform i) Linearity ii) Initial value theorem |  |  |  | 5 | CO 5 | L3 |
| 6 | Find Inverse Z-transform of the following using partial fraction expansion method. $X(z)=(1+2 z-1+z-2) /(1-1.5 z-1+0.5 z-2)$ |  |  |  | 5 | CO 5 | L3 |
| 7 | Check whether the system is causal or not ,the $\mathrm{H}(z)$ is given by ( $\mathrm{z} 3+$ $z) /(z+1)$. ii) $H(z)$ is given by ( $z / z 0 a$ ).,\|a|<1. |  |  |  | 5 | CO 5 | L3 |
| 8 | Determine the transfer function for the system described by the difference equation $y(n)_{0} y\left(n_{0} 1\right)=x(n)_{0} x\left(n_{0} 2\right)$. |  |  |  | 5 | CO 5 | L3 |
| 9 | find the inverse $z$-transform of $x(z)=1+3 z-1 / 1+3 z-1+2 z-2$ using residue method |  |  |  | 5 | CO 5 | L3 |
| 10 | Determine the inverse $z$ transform of the following function $x(z)=1 /(1+z-1)$ (1-z-1 )2 ROC : \|Z>1| |  |  |  | 5 | CO 5 | L3 |
| 11 | Find the $Z$ - transform of the signal (8) (i)x(n)=u(n) (ii) $\times(n)=A \cos \left(\omega_{0}\right) u(n)$ |  |  |  | 5 | CO 5 | L3 |
| 12 | Find the Unilateral Z-transform and R.O.C of $x(n)=\sin \omega 0 n u(n)$ |  |  |  | 5 | CO 5 | L3 |
| 13 | What is the time shifting property, differentiation property and convolution property of $Z$ transform . |  |  |  | 5 | CO 5 | L3 |
| 14 | State parseval's relation for Z transform |  |  |  | 5 | CO 5 | L3 |
| 15 | Define Z transform?What are the two types of Z transform? Define unilateral $Z$ transform |  |  |  | 5 | CO 5 | L3 |
| 16 | Find the Z-transform of the sequence, and sketch the ROC and pole zero location <br> i) $x(n)=(1 / 3)^{n} \sin (\Pi / 4 n) u(n)$ <br> ii) $x(n)=a^{n} u(n)+b^{n} u(-n-1)$ |  |  |  | 5 | CO 5 | L3 |
| 17 | What is ROC with respect to Z-transform? What are its properties |  |  |  | 5 | CO 5 | L3 |
| 18 | Find the inverse $z$ transform of the following by partial fraction method $X(z)=\left(z^{4}+z^{2}\right) /\left(z^{2}-3 / 4 z+1 / 8\right)$ <br> $\|z\|>1 / 2$ |  |  |  | 5 | CO 5 | L3 |
| 19 | Find the inverse $Z$ transform of $X(Z)$ by power series expansion method $X(Z)=1 / 1-1.5 Z^{-1}+0.5 Z^{-2}$ <br> ROC: $\|Z\|<1$ |  |  |  | 5 | CO 5 | L3 |
| 20 | Define Z-Transform for a general discrete time signal $\times[n]$. |  |  |  | 5 | CO 5 | L3 |
| 21 | What is ROC w.r.t. Z-Transform? |  |  |  | 5 | CO 5 | L3 |
| 22 | What are the properties of ROC? |  |  |  | 5 | CO 5 | L3 |
| 23 | What are the properties of Z-Transforms? |  |  |  | 5 | CO 5 | L3 |
| 24 | State and prove the properties of Unilateral Z-Transform and ROC. |  |  |  | 5 | CO 5 | L3 |
| 25 | Find the Z-Transform of $x[n]=-u(n-1)+(1 / 2)^{n} u(n)$ |  |  |  | 5 | CO 5 | L3 |
| 26 | Determine the Z-Transform, ROC, pole and zero locations for the following signals: a) $\left.x(n)=(1 / 2)^{n} u(n)+(-1 / 3)^{n} u(n) \quad b\right) x(n)=e^{i 2} 0^{n} u(n)$ |  |  |  | 5 | CO 5 | L3 |
| 27 | Find the inverse Z-Transform of , $\mathrm{H}(\mathrm{Z})=\left(1+Z^{-1}\right) /\left(1-0.9 e^{j \pi / 4} Z^{-1}\right)\left(1-0.9 \mathrm{e}^{-j \pi / 4} Z^{-1}\right)$ |  |  |  | 5 | CO 5 | L3 |
| 28 | Find the inverse Z-Transform assuming a) Signal is causal; b) Signal has |  |  |  | 5 | CO 5 | L3 |


|  | DTFT $1 /\left(1-1 / 2 Z^{-1}\right)+2 /\left(1-2 Z^{-1}\right)$ |  |  |  |
| :---: | :--- | :---: | :---: | :---: |
| 29 | A system is described by the difference equation y[n] $-y[n-1]+1 / 4$ y[n-2] <br> $=x[n]+1 / 4 \times[n-1]-1 / 8 \times[n-2] ~ a)$ Find the Transfer Function of the Inverse <br> System. b) Does a stable and causal inverse system exist? | 5 | CO 5 | L 3 |
| 30 | Define Z-Transform for a general discrete time signal $\times[n]$. | 5 | CO 5 | L 3 |

## F. EXAM PREPARATION

## 1. University Model Question Paper



| 8 | a | Using DTFT find the total solution to the difference equation for discrete time signal. $5 y(n+2)-6 y(n+1)+y(n)=0.8 u(n)$ | CO 4 | L3 | 8 |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | b | Find the fourier transform of the following. $x(n)=1 ;-2 \leq n \leq 2$ $=0$; Otherwise | CO 4 | L3 | 8 |
| 9 | a | Find the Z-transform of the following i) $x(n)=2 n u(-n-1)$ ii) $x(n)=(3) 2 n \quad u(-n)$ | CO 5 | L3 | 8 |
|  | b | Prove the following properties of Z-transform i) Linearity ii) Initial value theorem | CO 5 | L3 | 8 |
|  |  | OR |  |  |  |
| 10 | a | Find Inverse Z-transform of the following using partial fraction expansion method. $X(z)=\left(1+2 z^{-1}+z^{-2}\right) /\left(1-1.5 z^{-1}+0.5 z^{-2}\right)$ | CO 5 | L3 | 8 |
|  | b | Solve the following difference equation using unilateral Z-transform $Y(n)+$ $3 y(n-1)=x(n)$ with $x(n)=u(n)$ and the initial condition $y(-1)=1$ | CO 5 | L3 | 8 |
|  | b | With FSM model, explain the design and operation of automatic tea/ coffee vending machine. | CO 5 | L3 | 5 |
|  | c | Explain the assembly language based embedded firmware development with a diagram and mention its advantages and disadvantages. | CO 5 | L3 | 7 |
|  |  |  |  |  |  |

## 2. SEE Important Questions

| Course: Crs Code: |  | Signals \& Systems |  |  |  | Month / Year May /2018 |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 18EC45 | Sem: | 4 Marks: | 60 | Time: |  | 180 minutes |  |
|  | Note Answer all FIVE full questions. All questions carry equal marks. |  |  |  |  |  | - | - |  |
| Mod ule | Qno. Important Question |  |  |  |  |  | Marks | CO | Year |
| 1 | 1 | Distinguish between: i) Energy signal and Power signal ii)Continuous and Discrete time signals iii) Even and Odd signal iv)Periodic and non periodic signals |  |  |  |  | 6 | CO 1 | 2018 |
|  | 2 | Determine the even and Odd components of the signal i) $x(t)=1+t^{2}+t \tan t+\tan ^{2} t \cot t+\cot ^{3} t$ <br> ii) $x(t)=[s i n t+\operatorname{cost}]^{3}$ |  |  |  |  | 6 | CO 1 | 2018 |
|  | 3 | Determine whether the following signals are periodic, if periodic determine the fundamental period <br> i) $x(t)=\left[2 \cos ^{2}(\square t / 2)-1\right] \sin \Pi t \cos \Pi t$ <br> ii) $x(n)=\cos (n n / 7) \sin (\pi n / 3)$ |  |  |  |  | 6 | CO1 |  |
|  | 4 | Determine the following signal is Energy or Power signal i) $x(t)=e^{-a\|t\|} \quad a>0$ <br> ii) $x(t)=5^{+t}$ for $(-5,-4)$ 1 for ( $-4,4$ ) 5-t for $(4,5)$ o otherwise |  |  |  |  | 6 | CO1 | 2018 |
|  | 5 | Determine whether the system is i) Linear ii) Time Invariant iii) memoryless iv) causal v) stable <br> i) $y(t)=d / d t\left[l^{-t} x(t)\right\}$ <br> ii) $y(n)=x(k+2)$ |  |  |  |  | 6 | CO1 | 2018 |
|  |  |  |  |  |  |  |  |  |  |
| 2 | 1 | The impulse response of a continuous time LTI system is given by $h(t)=e^{2 n} u(n-1)$ and the input $x(n)=2 u(n)+5 u(n-1)$ |  |  |  |  | 8 | CO 2 | 2018 |
|  | 2 | A continuous time LTI system with unit impulse response $h(t)=u(t)$ and input $x(t)=e^{-a t} u(t) a>0$ find convolution of the signals |  |  |  |  | 6 | CO 2 | 2018 |
|  | 3 | Find the step response for the LTI system represented by the impulse response $h(n)=(1 / 2)^{n} u(n)$. |  |  |  |  | 8 | CO 2 | 2018 |
|  | 4 | consider a continuous time LTI system is represented by the impulse response $h(t)=e^{-3 t} u(t-1)$ determine whether it is i)stable ii) causal |  |  |  |  | 6 | CO 2 | 2018 |
|  | 5 | Solve the differential equation, $d^{2} y(t) / d t^{2}+3 d y(t) / d t+2 y(t)=2 x(t)$ with $y(0)=-1 d y(t) / d t$ with $t=0$ and $x(t)=\operatorname{cost} u(t)$ |  |  |  |  | 8 | CO 2 | 2018 |
|  |  |  |  |  |  |  |  |  |  |


| 3 | 1 | Determine Fourier transformation of following signals. i) $x(t)=e-a t u(t) ~ i i) x(t)=$ cost wot. | 6 | CO 3 | 2018 |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 2 | Find the frequency response and the impulse response of the system described by the differential equation. <br> $d^{2} y / d t^{2}+5 d y / d t+6 y=-d / d t x(t)$. | 8 | CO 3 | 2018 |
|  | 3 | State and explain parsavel's theorem | 6 | $\mathrm{CO}_{3}$ | 2018 |
|  | 4 | Obtain the fourier transform of the following signal $i) x(t)=e^{-a t} u(t) ; a>0$ ii) $)(t)=d e l t a(t)$ | 8 | $\mathrm{CO}_{3}$ | 2018 |
|  | 5 | obtain the fourier transform of $x(t)=t e^{-a t} u(t)$ | 6 | $\mathrm{CO}_{3}$ | 2018 |
| 4 | 1 | State and explain following DTFT properties I) Time shift ii) Linearity | 6 | CO 4 | 2018 |
|  | 2 | Determine the DTFT of the following signal, i) $x(n)=u(n)$ ii) $x(n)=2^{n} u(-n)$ | 6 | CO 4 | 2018 |
|  | 3 | Obtain the frequency response of the impulse response of the system described by the difference equation $y(n)-1 / 4 y(n-1)=3 x(n)-3 / 4 x(n-1)$ | 8 | CO 4 | 2018 |
|  | 4 | Find the fourier transform of the following. $x(n)=1 ;-2 \leq n \leq 2$ $=0$; Otherwise | 6 | CO 4 | 2018 |
|  | 5 | Obtain the DTFT of the signal $x[n]=2 n u(-n)$ | 6 | CO 4 | 2018 |
| 5 | 1 | Find the inverse Z-Transform assuming a) Signal is causal; b) Signal has DTFT $1 /\left(1-1 / 2 Z^{-1}\right)+2 /\left(1-2 Z^{-1}\right)$ | 5 | CO 5 | 2018 |
|  | 2 | What is z-transformation? List the properties of ROC. State and prove following properties i) Convolution ii) Time reversal | 8 | CO 5 | 2018 |
|  | 3 | Find Inverse Z-transform of the following using partial fraction expansion method. $X(z)=\left(1+2 z^{-1}+z^{-2}\right) /\left(1-1.5 z^{-1}+0.5 z^{-2}\right)$ | 6 | CO 5 | 2018 |
|  | 4 | Solve the following difference equation using unilateral Z-transform $Y(n)$ + $3 y(n-1)=x(n)$ with $x(n)=u(n)$ and the initial condition $y(-1)=1$ | 6 | CO 5 | 2018 |
|  | 5 | Find the $z$-transformation of i) $x(n)=n$ a nu( $-n$ ) ii) $x(n)=n \sin (\Pi / 2 n) u(-n)$ | 8 | CO 5 | 2018 |
|  | b | Mention the sequence of operations for embedding the firmware with a programmer and draw the interfacing diagram. | 6 | CO 5 | 2018 |

## Course Outcome Computation

## Academic Year:

Odd / Even semester


Attainment
LV Threshold : 3:>60\%, 2:>=50\% and <=60\%, 1: <=49\%
CO1 Computation : $(2+2+2+3) / 4=10 / 4=2.5$

## PO Computation

| Program Outcome | PO1 | PO 3 |  |  | PO 3 |  | PO1 |  | PO12 |  | PO12 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Weight of | 3 | 1 |  |  | 3 |  | 2 |  | 2 |  | 3 |  |
| CO-PO |  |  |  |  |  |  |  |  |  |  |  |  |
| Course Outcome | CO 1 |  | CO 2 |  | $\mathrm{CO}_{3}$ |  | CO 4 |  | CO 5 |  | CO6 |  |
| Test/Quiz/Lab QUESTION NO | T1 |  |  |  |  |  | T2 |  |  |  |  |  |
|  | Q1 | LV | Q2 | LV | Q3 | LV | Q1 | LV | Q2 | LV | Q3 | LV |
| MAX MARKS | 10 | - | 10 | - | 10 | - | 10 | - | 10 | - | 10 | - |
| USN-1 | 5 | 2 | 10 | 3 |  |  | 10 | 3 | 9 | 3 | 4 | 1 |
| USN-2 | 5 | 2 | 8 | 3 |  |  |  |  |  |  |  |  |
| USN-3 | 7 | 3 | 7 | 3 | 10 | 3 | 8 | 3 | 8 | 3 | 5 | 2 |
| USN-4 |  |  |  |  | 4 | 1 | 10 | 3 | 8 | 3 | 6 | 2 |
| USN-5 | 8 | 3 | 6 | 2 | 9 | 3 | 10 | 3 | 8 | 3 |  |  |
| USN-6 |  |  |  |  |  |  | 10 | 3 | 9 | 3 | 4 | 1 |
| Average Attainment |  | 2.5 |  | 2.75 |  | 2.33 |  | 3 |  | 3 |  | 1.5 |

